

avrSerial

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# Chapter 1

## Main Page

This is a serial library for many different Atmel AVR MCUs. It is using two FIFO Buffers per USART module for interrupt driven UART communication. XON/XOFF Flow control for incoming data can be enabled for all UART modules, it will operate independently for each.

Device-specific configuration is in [serial\\_device.h](#). You should be able to easily add new AVR MCUs. Just get the relevant register and bit names from the data-sheet.

A small test application is included. It will be built when calling either of these commands

```
make all
make test.hex
```

You can also flash it with

```
make program
```

just adjust your programmer type and port in the makefile.

For normal use, either include [serial.c](#), [serial.h](#) and [serial\\_device.h](#) in your project, or build a statically-linked library by calling

```
make lib
```

and linking this to your project, as well as including [serial.h](#).

The current Doxygen Documentation can be found in doc/ and [on the web](#) or as [PDF...](#)

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# Chapter 2

## Module Index

### 2.1 Modules

Here is a list of all modules:

UART Library . . . . . 7





# Chapter 3

## File Index

### 3.1 File List

Here is a list of all documented files with brief descriptions:

<a href="#">serial.c</a>	UART Library Implementation . . . . .	17
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<a href="#">serial_device.h</a>	UART Library device-specific configuration . . . . .	19
<b>test.c</b>	. . . . .	??



# Chapter 4

## Module Documentation

### 4.1 UART Library

UART Library enabling you to control all available UART Modules.

#### Files

- file [serial.c](#)  
*UART Library Implementation.*
- file [serial.h](#)  
*UART Library Header File.*
- file [serial\\_device.h](#)  
*UART Library device-specific configuration.*

#### Macros

- #define [RX\\_BUFFER\\_SIZE](#) 32  
*If you define this, a '\r' (CR) will be put in front of a '\n' (LF) when sending a byte.*
- #define [TX\\_BUFFER\\_SIZE](#) 16  
*TX Buffer Size in Bytes (Power of 2)*
- #define [FLOWCONTROL](#)  
*Defining this enables incoming XON XOFF (sends XOFF if rx buff is full)*
- #define [FLOWMARK](#) 5  
*Space remaining to trigger xoff/xon.*
- #define [XON](#) 0x11  
*XON Value.*
- #define [XOFF](#) 0x13  
*XOFF Value.*
- #define [BAUD](#)(baudRate, xtalCpu) ((xtalCpu)/((baudRate)\*16l)-1)  
*Calculate Baudrate Register Value.*

#### Functions

- uint8\_t [serialAvailable](#) (void)  
*Get number of available UART modules.*
- void [serialInit](#) (uint8\_t uart, uint16\_t baud)

- Initialize the UART Hardware.*

  - void `serialClose` (uint8\_t uart)
- Stop the UART Hardware.*

  - void `setFlow` (uint8\_t uart, uint8\_t on)
- Manually change the flow control.*

  - uint8\_t `serialHasChar` (uint8\_t uart)
- Check if a byte was received.*

  - uint8\_t `serialGetBlocking` (uint8\_t uart)
- Wait until a character is received.*

  - uint8\_t `serialGet` (uint8\_t uart)
- Read a single byte.*

  - uint8\_t `serialRxBufferFull` (uint8\_t uart)
- Check if the receive buffer is full.*

  - uint8\_t `serialRxBufferEmpty` (uint8\_t uart)
- Check if the receive buffer is empty.*

  - void `serialWrite` (uint8\_t uart, uint8\_t data)
- Send a byte.*

  - void `serialWriteString` (uint8\_t uart, const char \*data)
- Send a string.*

  - uint8\_t `serialTxBufferFull` (uint8\_t uart)
- Check if the transmit buffer is full.*

  - uint8\_t `serialTxBufferEmpty` (uint8\_t uart)
- Check if the transmit buffer is empty.*

#### 4.1.1 Detailed Description

UART Library enabling you to control all available UART Modules. With XON/XOFF Flow Control and buffered Receiving and Transmitting.

#### 4.1.2 Macro Definition Documentation

##### 4.1.2.1 #define BAUD( baudRate, xtalCpu ) ((xtalCpu)/((baudRate)\*16l)-1)

Calculate Baudrate Register Value.

Examples:

`test.c`.

Definition at line 45 of file serial.h.

##### 4.1.2.2 #define FLOWCONTROL

Defining this enables incoming XON XOFF (sends XOFF if rx buff is full)

Definition at line 62 of file serial.c.

##### 4.1.2.3 #define FLOWMARK 5

Space remaining to trigger xoff/xon.

Definition at line 64 of file serial.c.

Referenced by `serialGet()`.

#### 4.1.2.4 #define RX\_BUFFER\_SIZE 32

If you define this, a '\r' (CR) will be put in front of a '\n' (LF) when sending a byte.

Binary Communication will then be impossible!RX Buffer Size in Bytes (Power of 2)

Definition at line 54 of file serial.c.

Referenced by serialGet(), and serialRxBufferFull().

#### 4.1.2.5 #define TX\_BUFFER\_SIZE 16

TX Buffer Size in Bytes (Power of 2)

Definition at line 58 of file serial.c.

Referenced by serialTxBufferFull(), and serialWrite().

#### 4.1.2.6 #define XOFF 0x13

XOFF Value.

Definition at line 66 of file serial.c.

Referenced by setFlow().

#### 4.1.2.7 #define XON 0x11

XON Value.

Definition at line 65 of file serial.c.

Referenced by serialGet(), and setFlow().

### 4.1.3 Function Documentation

#### 4.1.3.1 uint8\_t serialAvailable ( void )

Get number of available UART modules.

##### Returns

number of modules

##### Examples:

[test.c](#).

Definition at line 113 of file serial.c.

```
113 {  
114     return UART_COUNT;  
115 }
```

#### 4.1.3.2 void serialClose ( uint8\_t uart )

Stop the UART Hardware.

##### Parameters

<i>uart</i>	UART Module to stop
-------------	---------------------

Definition at line 148 of file serial.c.

References serialTxBufferEmpty().

```

148         {
149     if (uart >= UART_COUNT)
150         return;
151
152     uint8_t sreg = SREG;
153     sei();
154     while (!serialTxBufferEmpty(uart));
155     while (*serialRegisters[uart][SERIALB] & (1 << serialBits[uart][SERIALUDRIE])); // Wait while Transmit
Interrupt is on
156     cli();
157     *serialRegisters[uart][SERIALB] = 0;
158     *serialRegisters[uart][SERIALC] = 0;
159     SREG = sreg;
160 }

```

#### 4.1.3.3 uint8\_t serialGet ( uint8\_t uart )

Read a single byte.

##### Parameters

<i>uart</i>	UART Module to read from
-------------	--------------------------

##### Returns

Received byte or 0

##### Examples:

[test.c](#).

Definition at line 217 of file serial.c.

References FLOWMARK, RX\_BUFFER\_SIZE, and XON.

Referenced by serialGetBlocking().

```

217         {
218     if (uart >= UART_COUNT)
219         return 0;
220
221     uint8_t c;
222
223     #ifdef FLOWCONTROL
224     rxBufferElements[uart]--;
225     if ((flow[uart] == 0) && (rxBufferElements[uart] <= FLOWMARK)) {
226         while (sendThisNext[uart] != 0);
227         sendThisNext[uart] = XON;
228         flow[uart] = 1;
229         if (shouldStartTransmission[uart]) {
230             shouldStartTransmission[uart] = 0;
231             *serialRegisters[uart][SERIALB] |= (1 << serialBits[uart][SERIALUDRIE]); // Enable Interrupt
232             *serialRegisters[uart][SERIALA] |= (1 << serialBits[uart][SERIALUDRE]); // Trigger Interrupt
233         }
234     }
235     #endif
236
237     if (rxRead[uart] != rxWrite[uart]) {
238         c = rxBuffer[uart][rxRead[uart]];
239         rxBuffer[uart][rxRead[uart]] = 0;
240         if (rxRead[uart] < (RX_BUFFER_SIZE - 1)) {
241             rxRead[uart]++;
242         } else {
243             rxRead[uart] = 0;
244         }
245         return c;
246     } else {
247         return 0;
248     }
249 }

```

4.1.3.4 `uint8_t serialGetBlocking ( uint8_t uart )`

Wait until a character is received.

## Parameters

<i>uart</i>	UART Module to read from
-------------	--------------------------

## Returns

Received byte

Definition at line 209 of file serial.c.

References `serialGet()`, and `serialHasChar()`.

```

209                                     {
210     if (uart >= UART_COUNT)
211         return 0;
212
213     while (!serialHasChar(uart));
214     return serialGet(uart);
215 }
```

4.1.3.5 `uint8_t serialHasChar ( uint8_t uart )`

Check if a byte was received.

## Parameters

<i>uart</i>	UART Module to check
-------------	----------------------

## Returns

1 if a byte was received, 0 if not

## Examples:

[test.c](#).

Definition at line 198 of file serial.c.

Referenced by `serialGetBlocking()`.

```

198                                     {
199     if (uart >= UART_COUNT)
200         return 0;
201
202     if (rxRead[uart] != rxWrite[uart]) { // True if char available
203         return 1;
204     } else {
205         return 0;
206     }
207 }
```

4.1.3.6 `void serialInit ( uint8_t uart, uint16_t baud )`

Initialize the UART Hardware.

## Parameters

<i>uart</i>	UART Module to initialize
<i>baud</i>	Baudrate. Use the <code>BAUD()</code> macro!

**Examples:**[test.c](#).

Definition at line 117 of file serial.c.

```

117                                     {
118     if (uart >= UART_COUNT)
119         return;
120
121     // Initialize state variables
122     rxRead[uart] = 0;
123     rxWrite[uart] = 0;
124     txRead[uart] = 0;
125     txWrite[uart] = 0;
126     shouldStartTransmission[uart] = 1;
127 #ifndef FLOWCONTROL
128     sendThisNext[uart] = 0;
129     flow[uart] = 1;
130     rxBufferElements[uart] = 0;
131 #endif
132
133     // Default Configuration: 8N1
134     *serialRegisters[uart][SERIALC] = (1 << serialBits[uart][SERIALUCSZ0]) | (1 << serialBits[uart][
SERIALUCSZ1]);
135
136     // Set baudrate
137 #if SERIALBAUDBIT == 8
138     *serialRegisters[uart][SERIALUBRRH] = (baud >> 8);
139     *serialRegisters[uart][SERIALUBRRL] = baud;
140 #else
141     *serialBaudRegisters[uart] = baud;
142 #endif
143
144     *serialRegisters[uart][SERIALB] = (1 << serialBits[uart][SERIALRXCIE]); // Enable Interrupts
145     *serialRegisters[uart][SERIALB] |= (1 << serialBits[uart][SERIALRXEN]) | (1 << serialBits[uart][
SERIALTXEN]); // Enable Receiver/Transmitter
146 }

```

**4.1.3.7 uint8\_t serialRxBufferEmpty ( uint8\_t uart )**

Check if the receive buffer is empty.

**Parameters**

<i>uart</i>	UART Module to check
-------------	----------------------

**Returns**

1 if buffer is empty, 0 if not.

Definition at line 258 of file serial.c.

```

258                                     {
259     if (uart >= UART_COUNT)
260         return 0;
261
262     if (rxRead[uart] != rxWrite[uart]) {
263         return 0;
264     } else {
265         return 1;
266     }
267 }

```

**4.1.3.8 uint8\_t serialRxBufferFull ( uint8\_t uart )**

Check if the receive buffer is full.



## Parameters

<i>uart</i>	UART Module to check
-------------	----------------------

## Returns

1 if buffer is full, 0 if not

Definition at line 251 of file serial.c.

References RX\_BUFFER\_SIZE.

```
251                                     {
252     if (uart >= UART_COUNT)
253         return 0;
254
255     return ((rxWrite[uart] + 1) == rxRead[uart]) || ((rxRead[uart] == 0) && ((rxWrite[uart] + 1) ==
256         RX_BUFFER_SIZE));
}
```

#### 4.1.3.9 uint8\_t serialTxBufferEmpty ( uint8\_t *uart* )

Check if the transmit buffer is empty.

## Parameters

<i>uart</i>	UART Module to check
-------------	----------------------

## Returns

1 if buffer is empty, 0 if not.

Definition at line 317 of file serial.c.

Referenced by serialClose().

```
317                                     {
318     if (uart >= UART_COUNT)
319         return 0;
320
321     if (txRead[uart] != txWrite[uart]) {
322         return 0;
323     } else {
324         return 1;
325     }
326 }
```

#### 4.1.3.10 uint8\_t serialTxBufferFull ( uint8\_t *uart* )

Check if the transmit buffer is full.

## Parameters

<i>uart</i>	UART Module to check
-------------	----------------------

## Returns

1 if buffer is full, 0 if not

Definition at line 310 of file serial.c.

References TX\_BUFFER\_SIZE.

Referenced by serialWrite().

```

310                                     {
311     if (uart >= UART_COUNT)
312         return 0;
313
314     return (((txWrite[uart] + 1) == txRead[uart]) || ((txRead[uart] == 0) && ((txWrite[uart] + 1) ==
TX_BUFFER_SIZE)));
315 }

```

#### 4.1.3.11 void serialWrite ( uint8\_t uart, uint8\_t data )

Send a byte.

##### Parameters

<i>uart</i>	UART Module to write to
<i>data</i>	Byte to send

##### Examples:

[test.c](#).

Definition at line 273 of file serial.c.

References serialTxBufferFull(), and TX\_BUFFER\_SIZE.

Referenced by serialWriteString().

```

273                                     {
274     if (uart >= UART_COUNT)
275         return;
276
277     #ifdef SERIALINJECTCR
278     if (data == '\n') {
279         serialWrite(uart, '\r');
280     }
281     #endif
282     while (serialTxBufferFull(uart));
283
284     txBuffer[uart][txWrite[uart]] = data;
285     if (txWrite[uart] < (TX_BUFFER_SIZE - 1)) {
286         txWrite[uart]++;
287     } else {
288         txWrite[uart] = 0;
289     }
290     if (shouldStartTransmission[uart]) {
291         shouldStartTransmission[uart] = 0;
292         *serialRegisters[uart][SERIALB] |= (1 << serialBits[uart][SERIALUDRIE]); // Enable Interrupt
293         *serialRegisters[uart][SERIALA] |= (1 << serialBits[uart][SERIALUDRE]); // Trigger Interrupt
294     }
295 }

```

#### 4.1.3.12 void serialWriteString ( uint8\_t uart, const char \* data )

Send a string.

##### Parameters

<i>uart</i>	UART Module to write to
<i>data</i>	Null-Terminated String

##### Examples:

[test.c](#).

Definition at line 297 of file serial.c.

References serialWrite().

```

297                                     {
298     if (uart >= UART_COUNT)
299         return;
300
301     if (data == 0) {
302         serialWriteString(uart, "NULL");
303     } else {
304         while (*data != '\0') {
305             serialWrite(uart, *data++);
306         }
307     }
308 }

```

#### 4.1.3.13 void setFlow ( uint8\_t uart, uint8\_t on )

Manually change the flow control.

Flow Control has to be compiled into the library!

##### Parameters

<i>uart</i>	UART Module to operate on
<i>on</i>	1 of on, 0 if off

Definition at line 163 of file serial.c.

References XOFF, and XON.

```

163                                     {
164     if (uart >= UART_COUNT)
165         return;
166
167     if (flow[uart] != on) {
168         if (on == 1) {
169             // Send XON
170             while (sendThisNext[uart] != 0);
171             sendThisNext[uart] = XON;
172             flow[uart] = 1;
173             if (shouldStartTransmission[uart]) {
174                 shouldStartTransmission[uart] = 0;
175                 *serialRegisters[uart][SERIALB] |= (1 << serialBits[uart][SERIALUDRIE]);
176                 *serialRegisters[uart][SERIALA] |= (1 << serialBits[uart][SERIALUDRE]); // Trigger
177             Interrupt
178             } else {
179                 // Send XOFF
180                 sendThisNext[uart] = XOFF;
181                 flow[uart] = 0;
182                 if (shouldStartTransmission[uart]) {
183                     shouldStartTransmission[uart] = 0;
184                     *serialRegisters[uart][SERIALB] |= (1 << serialBits[uart][SERIALUDRIE]);
185                     *serialRegisters[uart][SERIALA] |= (1 << serialBits[uart][SERIALUDRE]); // Trigger
186                 Interrupt
187                 }
188                 // Wait till it's transmitted
189                 while (*serialRegisters[uart][SERIALB] & (1 << serialBits[uart][SERIALUDRIE]));
190             }
191 }

```



# Chapter 5

## File Documentation

### 5.1 serial.c File Reference

UART Library Implementation.

```
#include <avr/io.h>
#include <avr/interrupt.h>
#include <stdint.h>
#include "serial.h"
#include "serial_device.h"
```

#### Macros

- `#define RX_BUFFER_SIZE 32`  
*If you define this, a '\r' (CR) will be put in front of a '\n' (LF) when sending a byte.*
- `#define TX_BUFFER_SIZE 16`  
*TX Buffer Size in Bytes (Power of 2)*
- `#define FLOWCONTROL`  
*Defining this enables incoming XON XOFF (sends XOFF if rx buff is full)*
- `#define FLOWMARK 5`  
*Space remaining to trigger xoff/xon.*
- `#define XON 0x11`  
*XON Value.*
- `#define XOFF 0x13`  
*XOFF Value.*

#### Functions

- `uint8_t serialAvailable` (void)  
*Get number of available UART modules.*
- `void serialInit` (uint8\_t uart, uint16\_t baud)  
*Initialize the UART Hardware.*
- `void serialClose` (uint8\_t uart)  
*Stop the UART Hardware.*
- `void setFlow` (uint8\_t uart, uint8\_t on)  
*Manually change the flow control.*
- `uint8_t serialHasChar` (uint8\_t uart)

- Check if a byte was received.*

  - `uint8_t serialGetBlocking` (`uint8_t uart`)
    - Wait until a character is received.*
  - `uint8_t serialGet` (`uint8_t uart`)
    - Read a single byte.*
  - `uint8_t serialRxBufferFull` (`uint8_t uart`)
    - Check if the receive buffer is full.*
  - `uint8_t serialRxBufferEmpty` (`uint8_t uart`)
    - Check if the receive buffer is empty.*
  - `void serialWrite` (`uint8_t uart`, `uint8_t data`)
    - Send a byte.*
  - `void serialWriteString` (`uint8_t uart`, `const char *data`)
    - Send a string.*
  - `uint8_t serialTxBufferFull` (`uint8_t uart`)
    - Check if the transmit buffer is full.*
  - `uint8_t serialTxBufferEmpty` (`uint8_t uart`)
    - Check if the transmit buffer is empty.*

### 5.1.1 Detailed Description

UART Library Implementation.

Definition in file [serial.c](#).

## 5.2 serial.h File Reference

UART Library Header File.

### Macros

- `#define BAUD(baudRate, xtalCpu) ((xtalCpu)/((baudRate)*16L)-1)`
  - Calculate Baudrate Register Value.*

### Functions

- `uint8_t serialAvailable` (`void`)
  - Get number of available UART modules.*
- `void serialInit` (`uint8_t uart`, `uint16_t baud`)
  - Initialize the UART Hardware.*
- `void serialClose` (`uint8_t uart`)
  - Stop the UART Hardware.*
- `void setFlow` (`uint8_t uart`, `uint8_t on`)
  - Manually change the flow control.*
- `uint8_t serialHasChar` (`uint8_t uart`)
  - Check if a byte was received.*
- `uint8_t serialGet` (`uint8_t uart`)
  - Read a single byte.*
- `uint8_t serialGetBlocking` (`uint8_t uart`)
  - Wait until a character is received.*
- `uint8_t serialRxBufferFull` (`uint8_t uart`)

- Check if the receive buffer is full.*
- uint8\_t [serialRxBufferEmpty](#) (uint8\_t uart)  
*Check if the receive buffer is empty.*
- void [serialWrite](#) (uint8\_t uart, uint8\_t data)  
*Send a byte.*
- void [serialWriteString](#) (uint8\_t uart, const char \*data)  
*Send a string.*
- uint8\_t [serialTxBufferFull](#) (uint8\_t uart)  
*Check if the transmit buffer is full.*
- uint8\_t [serialTxBufferEmpty](#) (uint8\_t uart)  
*Check if the transmit buffer is empty.*

### 5.2.1 Detailed Description

UART Library Header File.

Definition in file [serial.h](#).

## 5.3 serial\_device.h File Reference

UART Library device-specific configuration.

### 5.3.1 Detailed Description

UART Library device-specific configuration. Contains Register and Bit Positions for different AVR devices.

Definition in file [serial\\_device.h](#).





## Chapter 6

# Example Documentation

### 6.1 test.c

Initializes all available UART Modules. Then prints a welcome message on each and waits for incoming characters, which will be repeated on the UART module they were received on.

```
/*
 * test.c
 *
 * Copyright (c) 2012, Thomas Buck <xythobuz@me.com>
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 *
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 * modification, are permitted provided that the following conditions
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 * PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON ANY THEORY OF
 * LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT (INCLUDING
 * NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
 * SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
 */
#include <avr/io.h>
#include <avr/interrupt.h>
#include <stdint.h>

#include "serial.h"

int main(void) {
    // Initialize UART modules
    for (int i = 0; i < serialAvailable(); i++) {
        serialInit(i, BAUD(38400, F_CPU));
    }

    // Enable Interrupts
    sei();

    // Print Welcome Message
    for (int i = 0; i < serialAvailable(); i++) {
        serialWriteString(i, "Hello from UART");
        serialWrite(i, i + '0');
        serialWriteString(i, "... :\n");
    }

    // Wait for incoming bytes
    for(;;) {
        for (int i = 0; i < serialAvailable(); i++) {
            if (serialHasChar(i)) {
```

```
        serialWrite(i, serialGet(i));
    }
}
return 0;
}
```

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